# Differential Forms in Algebraic Topology Integration on Manifolds

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### References

### Main References

- Section 23 of Tu2011.
- Section 3 of Bott-Tu.

#### Remark

Throughout this section we assume familiarity with measure theory and Lebesgue's integral on  $\mathbb{R}^n$ .

#### Definition

Let  $\omega = f(x)dx^1 \wedge \cdots \wedge dx^n$  be a smooth *n*-form on an open  $U \subset \mathbb{R}^n$  with coordinates  $x^1, \dots, x^n$ . The *integral* of  $\omega$  over a Borel set  $A \subset U$  is defined by

$$\int_A \omega = \int_A f(x) dx^1 \wedge \cdots \wedge dx^n := \int_A f(x) dx.$$

### Reminder (see Section 21)

Let  $\phi: V \to U$  be a diffeomorphism between open subsets of  $\mathbb{R}^n$ .

- $\phi$  is orientation-preserving if and only if  $\det(J(\phi)) > 0$  on V.
- It is orientation-reversing if and only if  $\det(J(\phi)) < 0$  on V.

Here  $J(\phi)$  is the Jacobian of  $\phi$ .

#### **Facts**

Let  $\phi: V \to U$  be a diffeomorphism between open subsets of  $\mathbb{R}^n$ . We use coordinates  $(x^1, \dots, x^n)$  on U and coordinates  $(y^1, \dots, y^n)$  on V. Set  $\phi^i = x^i \circ \phi = \phi^* x^i$ .

• Let  $\omega = f(x)dx^1 \wedge \cdots \wedge dx^n$  be a  $C^{\infty}$  *n*-form on U. As pullback commutes with wedge product and differential,

$$\phi^*\omega = \phi^* (f dx^1 \wedge \dots \wedge dx^n) = (\phi^* f) (\phi^* dx^1) \wedge \dots \wedge (\phi^* dx^n),$$
  
=  $(f \circ \phi) d(\phi^* x^1) \wedge \dots \wedge d(\phi^* x^n),$   
=  $(f \circ \phi) d\phi^1 \wedge \dots \wedge d\phi^n.$ 

 By using the local expression for wedge of differentials (Proposition 18.3), we get

$$\phi^*\omega = (f \circ \phi) \frac{\partial (\phi^1, \dots, \phi^n)}{\partial (y^1, \dots, y^n)} dy^1 \wedge \dots \wedge dy^n$$
$$= (f \circ \phi) \det (J(\phi)) dy^1 \wedge \dots \wedge dy^n.$$

#### Facts (Continued)

 $\bullet$  Assume that the diffeomorphism  $\phi$  is orientation-preserving or orientation-reversing. Then

$$\phi^*\omega = (f \circ \phi) \det (J(\phi)) dy^1 \wedge \cdots \wedge dy^n,$$
  
=  $\pm (f \circ \phi) |\det (J(\phi))| dy^1 \wedge \cdots \wedge dy^n,$ 

where the sign  $\pm$  depends on whether  $\phi$  is orientation-preserving or orientation-reversing.

• By using the usual change of variable formula, we get

$$\int_{V} \phi^* \omega = \pm \int_{\phi^{-1}(U)} (f \circ \phi) \big| \det \big( J(\phi) \big) \big| dy = \pm \int_{U} f dx = \pm \int_{U} \omega.$$

Therefore, we obtain:

#### Lemma

Let  $\phi: V \to U$  be a diffeomorphism between open subsets of  $\mathbb{R}^n$ , and  $\omega$  a smooth n-form on U.

• If  $\phi$  is orientation-preserving, then

$$\int_{V} \phi^* \omega = \int_{U} \omega.$$

• If  $\phi$  is orientation-reversing, then

$$\int_{V} \phi^* \omega = - \int_{U} \omega.$$

#### Definition

If M is a smooth manifold, we denote by  $\Omega_c^k(M)$  the space of smooth k-forms with compact support.

#### Definition

Assume M is oriented and is equipped with an oriented atlas  $\{(U_{\alpha},\phi_{\alpha})\}$ . Set  $n=\dim M$ . Let  $(U,\phi)$  be chart in this atlas. The integral of any top-form  $\omega\in\Omega^n_c(U)$  is defined by

$$\int_{U} \omega := \int_{\phi(U)} (\phi^{-1})^* \omega.$$

#### Remark

Let  $(U, \psi)$  be another chart with same domain in the oriented atlas.

- The transition map  $\phi \circ \psi^{-1} : \psi(U) \to \phi(U)$  is an orientation-preserving diffeomorphism, since the charts  $(U, \phi)$  and  $(U, \psi)$  belong to the same oriented atlas.
- Thus, by the previous lemma we have

$$\int_{\psi(U)} (\psi^{-1})^* \omega = \int_{\psi(U)} (\phi \circ \psi^{-1})^* [(\phi^{-1})^* \omega] = \int_{\phi(U)} (\phi^{-1})^* \omega$$

• This shows that the integral  $\int_U \omega$  is well-defined and independent of the choice of the coordinate system  $\phi$  on U.

#### **Facts**

Let  $\omega \in \Omega_c^n(M)$  and  $\{\rho_\alpha\}$  a  $C^\infty$  partition of unity subordinated to the open cover  $\{U_\alpha\}$ .

 $\bullet$  As  $\omega$  has compact support, we have

$$\omega = \sum_{\alpha} \rho_{\alpha} \omega,$$

where the sum is actually finite (see Problem 18.6).

- By Problem 18.4 supp $(\rho_{\alpha}\omega) = \operatorname{supp} \rho_{\alpha} \cap \operatorname{supp} \omega$ , and so  $\rho_{\alpha}\omega$  has compact support.
- Thus, the integral  $\int_{U_{\alpha}} \rho_{\alpha} \omega$  is well defined.

#### Definition

Let  $\omega \in \Omega_c^n(M)$ . The integral of  $\omega$  over M is defined by

$$\int_{M} \omega = \sum_{\alpha} \int_{U_{\alpha}} \rho_{\alpha} \omega.$$

#### Remark

The integral  $\int_M \omega$  is well defined and independent of the partition of unity  $\{\rho_\alpha\}$  (see Tu's book).

#### Proposition (Proposition 23.10)

Let -M be the manifold M with the opposite orientation. Then, for every  $\omega \in \Omega^n_c(M)$ , we have

$$\int_{-M} \omega = -\int_{M} \omega.$$

#### Remark

The treatment of integration of differential forms on oriented manifolds extends *verbatim* to differential forms on oriented manifolds with boundary.

### Definition (Domain of Integration; see Definition 23.6)

A subset  $D \subset \mathbb{R}^n$  is called a *domain of integration* if it is bounded and its topological boundary has measure zero.

### Definition (Parametrized Set)

A parametrized set in an oriented *n*-manifold M is a subset A together with a  $C^{\infty}$ -map  $F:D\to M$ , where D is a compact domain of integration in  $\mathbb{R}^n$  such that:

- (i) F(D) = A.
- (ii) F restricts to an orientation-preserving diffeomorphism from Int(D) to F(Int(D)).

The map  $F: D \rightarrow A$  is called a parametrization of A.

#### Remark

By smooth invariance of domain for manifolds, F(Int(D)) must be an open subset of M (see Remark 22.5).

#### Definition

Let A be a parametrized set in M and  $F: D \to M$  a parametrization. For any  $\omega \in \Omega^n(M)$ , the integral of  $\omega$  over A is defined by  $\int_{\mathbf{A}} \omega := \int_{\mathbf{D}} F^* \omega.$ 

Remarks

- The integral  $\int_{\Lambda} \omega$  is well defined and independent of the parametrization F.
- 2 We don't need to assume  $\omega$  to have compact support in the above definition.

## Integration over a Zero-Dimensional Manifold

#### Remarks

- A zero-dimensional manifold is a discrete countable set of points.
- A connected zero-dimensional manifold is just a point. In this case there are two classes [1] and [-1] of non-zero 0-forms.
- More generally, an orientation on a 0-dimensional manifold is given by a function on M that assigns the values  $\pm 1$ .

### Integration over a Zero-Dimensional Manifold

#### **Facts**

- A compact oriented 0-dimensional manifold M is a finite unions of points oriented by +1 and -1.
- We write  $M = \sum_i p_i \sum_i q_i$ .
- The integral of a function  $f: M \to \mathbb{R}$  is then defined by

$$\int_{M} f = \sum_{i} f(p_i) - \sum_{j} f(q_j).$$

### Stokes's Theorem

### Theorem (Stokes's Theorem; Theorem 23.12)

Let M be an oriented manifold with boundary. We endow  $\partial M$  with its boundary orientation. Then, for every  $\omega \in \Omega_c^{n-1}(M)$ , we have

$$\int_{M} d\omega = \int_{\partial M} \omega.$$

#### Notation

If  $\mathbf{F} = \langle P, Q, R \rangle$  is a vector field on  $\mathbb{R}^3$  and  $\mathbf{r} = \langle x, y, z \rangle$  is the radial vector field, then  $\mathbf{F} \cdot d\mathbf{r}$  is the 1-form Pdx + Qdy + Rdz.

### Theorem (Fundamental theorem for line integrals; Theorem 23.13)

Let C be a smooth curve in  $\mathbb{R}^3$  with parametrization  $\mathbf{r}(t) = (x(t), y(t), z(t))$ ,  $a \le t \le b$ . For any smooth function f on  $\mathbb{R}^3$  we have

$$\int_{C} \operatorname{grad} f \cdot d\mathbf{r} = f(\mathbf{r}(b)) - f(\mathbf{r}(a)).$$

#### Proof.

• Apply Stokes's theorem to M = C and  $\omega = f$  to get:

$$\int_C df = \int_{\partial C} f.$$

We have

$$\int_{C} df = \int_{C} \left\{ \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz \right\} = \int_{C} \operatorname{grad} f \cdot d\mathbf{r},$$

$$\int_{\partial C} f = f \Big|_{\mathbf{r}(a)}^{\mathbf{r}(b)} = f(\mathbf{r}(b)) - f(\mathbf{r}(a)).$$

This gives the result.

### Theorem (Green's Theorem; Theorem 23.14)

Let D be a planar region with boundary  $\partial D$ . For any smooth functions P and Q near D we have

$$\int_{\partial D} (Pdx + Qdy) = \int_{D} \left\{ \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right\} dxdy.$$

#### Proof.

• Stokes's theorem for M = D and  $\omega = Pdx + Qdy$  gives

$$\int_{\partial D} \big( P dx + Q dy \big) = \int_{D} d \big( P dx + Q dy \big).$$

We have

$$d(Pdx + Qdy) = dP \wedge dx + dQ \wedge dy$$
$$= \frac{\partial P}{\partial y} dy \wedge dx + \frac{\partial Q}{\partial x} dx \wedge dy$$
$$= \left\{ \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right\} dx \wedge dy.$$

• Thus, by the very definition of the integral of a top form,

$$\int_{D} d(Pdx + Qdy) = \int_{D} \left\{ \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right\} dxdy.$$

This gives the result.