

# Differentiable Manifolds

## §19. The Exterior Derivative

Sichuan University, Fall 2020

## Reminder: Exterior Derivative on an Open Set

### Definition (Exterior derivative on open set)

Let  $U$  be an open subset of  $\mathbb{R}^n$ . The *exterior derivative*  $d : \Omega^*(U) \rightarrow \Omega^*(U)$  is defined as follows:

- For  $k = 0$  the exterior derivative of a 0-form (i.e., a  $C^\infty$  function)  $f$  on  $U$  is its differential, i.e.,  $df = \sum \frac{\partial f}{\partial x^i} dx^i$ .
- For  $k \geq 1$ , the exterior derivative  $\omega = \sum a_I dx^I \in \Omega^k(U)$  is

$$d\omega = \sum da_I \wedge dx^I = \sum_I \left( \sum_j \frac{\partial a_I}{\partial x^j} dx^j \right) \wedge dx^I.$$

### Remarks

- If  $\omega \in \Omega^k(U)$ , then  $d\omega \in \Omega^{k+1}(U)$ .
- In particular,  $d\omega = 0$  for all  $\omega \in \Omega^n(U)$ .

## Reminder: Exterior Derivative on an Open Set

### Reminder (Graded Algebras)

An algebra  $A$  over a field  $\mathbb{K}$  is called *graded* when it can be decomposed as

$$A = \bigoplus_{k=0}^{\infty} A^k,$$

where the  $A^k$  are subspaces such that the multiplication maps  $A^k \times A^\ell$  to  $A^{k+\ell}$ .

### Reminder (Antiderivation of a Graded Algebra; see Section 4)

Let  $A = \bigoplus_{k=0}^{\infty} A^k$  be a graded algebra over a field  $\mathbb{K}$ .

- An *antiderivation* of  $A$  is any linear map  $D : A \rightarrow A$  such that

$$D(ab) = (Da)b + (-1)^k aDb \quad \text{for all } a \in A^k \text{ and } b \in A.$$

- We say that  $D$  has *degree*  $m$  when  $D(A^k) \subset A^{k+m}$  for all  $k$ .

## Reminder: Exterior Derivative on an Open Set

### Reminder

$\Omega^*(U) = \bigoplus_{k=0}^n \Omega^k(U)$  is a graded algebra over  $\mathbb{R}$ .

### Reminder (Proposition 4.7)

The exterior derivative  $d : \Omega^*(U) \rightarrow \Omega^*(U)$  satisfies the following properties:

(i) It is an antiderivation of degree 1, i.e.,

$$d(\omega \wedge \tau) = (d\omega) \wedge \tau + (-1)^{\deg \omega} \omega \wedge d\tau.$$

(ii)  $d^2 = 0$ , i.e.,  $d(d\omega) = 0$  for all  $\omega \in \Omega^*(U)$ .

(iii) If  $f \in C^\infty(U)$  and  $X \in \mathcal{X}(U)$ , then  $(df)(X) = Xf$ .

### Reminder (Proposition 4.8)

The exterior derivative is the unique map  $D : \Omega^*(U) \rightarrow \Omega^*(U)$  that satisfies the properties (i)–(iii) above.

# Exterior Derivative on a Manifold

## Reminder

Let  $M$  be a smooth manifold of dimension  $n$ . Then the exterior algebra of differential forms  $\Omega^*(M) = \bigoplus_{k=0}^n \Omega^k(M)$  is a graded algebra.

## Definition

An *exterior derivative* on a manifold  $M$  is a linear map  $D : \Omega^*(M) \rightarrow \Omega^*(M)$  satisfying the following properties:

- (i) It is an antiderivation of degree 1.
- (ii)  $D \circ D = 0$ .
- (iii) On  $\Omega^0(M) = C^\infty(M)$  it agrees with the differential of functions, i.e.,  $Df = df$  for all  $f \in C^\infty(M)$ .

## Theorem (Theorem 19.4)

*There is a unique exterior derivative  $d : \Omega^*(M) \rightarrow \Omega^*(M)$ .*

# Construction of the Exterior Derivative

## Reminder

Let  $(U, x^1, \dots, x^n)$  be a chart for  $M$ .

- $\{dx^I; I \in \mathcal{I}_{k,n}\}$  is a smooth frame of  $\Omega^k(M)$  over  $U$ .
- Every smooth  $k$ -form  $\omega$  on  $U$  can be uniquely written as  $\omega = \sum a_I dx^I$  with  $a_I$  in  $C^\infty(U)$ .

# Construction of the Exterior Derivative

## Definition

Let  $(U, x^1, \dots, x^n)$  be a chart. Define  $d_U : \Omega^*(U) \rightarrow \Omega^*(U)$  by

(i) If  $f \in C^\infty(U) = \Omega^0(U)$ , then

$$d_U f = df = \sum \frac{\partial f}{\partial x^i} dx^i.$$

(ii) If  $\omega = \sum a_I dx^I \in \Omega^k(U)$ ,  $k \geq 1$ , then

$$d\omega = \sum_I da_I \wedge dx^I.$$

In the same way as in the case of an open set of  $\mathbb{R}^n$  we get:

## Lemma

$d_U : \Omega^*(U) \rightarrow \Omega^*(U)$  is the unique exterior derivative on  $U$ .

# Construction of the Exterior Derivative

## Remark

- The proof of uniqueness in Tu's book lacks details.
- Tu's arguments require to show that if  $D : \Omega^*(M) \rightarrow \Omega^*(M)$  is an exterior derivative, then

$$D(dx^I) = 0 \quad \forall I \in \mathcal{I}_{k,n}, \quad k \geq 1.$$

This can be proved by induction on  $k$ .

- $k = 1$ :  $D(dx^i) = D \circ D(x^i) = 0$  since  $D = d$  on  $C^\infty(M)$ .
- Assume the result for  $k$ . Let  $I = (i_1, \dots, i_{k+1}) \in \mathcal{I}_{k+1,n}$  and set  $J = (i_2, \dots, i_{k+1}) \in \mathcal{I}_{k,n}$ . We have

$$dx^I = dx^{i_1} \wedge dx^{i_2} \wedge \dots \wedge dx^{i_{k+1}} = dx^{i_1} \wedge dx^J.$$

- As  $D$  is an antiderivation, we get

$$D(dx^I) = D(dx^{i_1} \wedge dx^J) = D(dx^{i_1}) \wedge dx^J - dx^{i_1} \wedge D(dx^J) = 0,$$

since  $D(dx^{i_1}) = 0$  and  $D(dx^J) = 0$ .

# Construction of the Exterior Derivative

## Remark (Continued)

- Once it has been established that  $D(dx^I) = 0$ , it can be shown that  $D = d_U$  as in Tu's book.
- Let  $\omega = \sum a_I dx^I \in \Omega^k(U)$ . As  $D$  is an antiderivation and agrees with the differential on functions, we get

$$\begin{aligned} d\omega &= \sum D(a_I dx^I) = \sum D(a_I) \wedge dx^I + \sum a_I D(dx^I) \\ &= \sum da^I \wedge dx^I \\ &= d_U \omega. \end{aligned}$$

- This shows that  $d_U$  is the only exterior derivative on  $U$ .

# Construction of the Exterior Derivative

## Facts

Let  $\omega \in \Omega^k(M)$ . Let  $(U, x^1, \dots, x^n)$  and  $(V, y^1, \dots, y^n)$  be charts for  $M$  near  $p \in M$ .

- Write  $\omega = \sum a_I dx^I$  on  $U$  and  $\omega = \sum b_I dy^I$  on  $V$ . Then on  $U \cap V$  we have

$$\omega = \sum a_I dx^I = \sum b_I dy^I.$$

- In particular, on  $U \cap V$  we get

$$\sum da_I \wedge dx^I = d_{U \cap V}(\omega|_{U \cap V}) = \sum db_I dy^I.$$

- As  $p \in U \cap V$ , we obtain

$$d_U(\omega|_U)_p = \sum (da_I \wedge dx^I)_p = \sum (db_I \wedge dy^I)_p = d_V(\omega|_V)_p.$$

# Construction of the Exterior Derivative

## Consequence

$d_U(\omega|_U)_p$  depends only on  $\omega$  and  $p$ , not on  $U$ .

## Definition

The map  $d : \Omega^*(M) \rightarrow \Omega^*(M)$  is defined as follows: if  $\omega \in \Omega^k(M)$  and  $p \in M$ , then

$$(d\omega)_p = d_U(\omega|_U)_p,$$

where  $U$  is the domain of any chart near  $p$ .

## Theorem (Theorem 19.4)

*The map  $d : \Omega^*(M) \rightarrow \Omega^*(M)$  is the unique exterior derivative on  $M$ .*

# Construction of the Exterior Derivative

## Definition

$d : \Omega^*(M) \rightarrow \Omega^*(M)$  is called the *exterior derivative* of  $M$ .

## Remark

Let  $\omega \in \Omega^k(U)$  and  $(U, x^1, \dots, x^n)$  a chart for  $M$ .

- By definition  $(d\omega)_p = d_U(\omega|_U)_p$  for all  $p \in U$ . Thus,

$$(d\omega)|_U = d_U(\omega|_U).$$

- In particular, if  $\omega = \sum a_I dx^I$  on  $U$ , then

$$(d\omega)|_U = d_U(\omega|_U) = \sum da^I \wedge dx^I \quad \text{on } U.$$

# Exterior Differentiation Under a Pullback

## Reminder (see slides on Section 18)

Let  $F : N \rightarrow M$  be a smooth map.

- If  $\omega$  is a  $k$ -form on  $M$ , then its pullback  $F^*\omega$  is the  $k$ -form on  $N$  given by

$$\begin{aligned}(F^*\omega)_p(v_1, \dots, v_k) &= ((F_{*,p})^*\omega_p)(v_1, \dots, v_k) \\ &= \omega_p(F_{*,p}v_1, \dots, F_{*,p}v_k), \quad v_i \in T_pN.\end{aligned}$$

- If  $\omega$  is a smooth form on  $M$ , then  $F^*\omega$  is a smooth form on  $N$ .

# Exterior Differentiation Under a Pullback

Exterior differentiation commutes with pullback. Namely, we have:

## Proposition (Proposition 19.5)

*Let  $F : N \rightarrow M$  be a smooth map. If  $\omega \in \Omega^k(M)$ , then*

$$F^*(d\omega) = d(F^*\omega).$$

## Remark

- In Tu's book, Proposition 19.5 is used to show that smoothness of  $k$ -forms is preserved by pullback.
- This is not fully rigorous since in order to make sense Proposition 19.5 requires the smoothness of pullbacks of smooth forms.
- Anyway, smoothness of pullbacks of forms can be proved without using Proposition 19.5 (see slides on Section 18).

# Restriction of $k$ -Forms to Submanifolds

## Reminder

Let  $S$  be an immersed submanifold in  $M$ .

- The inclusion  $i : S \rightarrow M$  is an immersion, and so its differential  $i_{*,p} : T_p S \rightarrow T_p M$  is an injection for every  $p \in S$ .
- This allows us to identify  $T_p S$  with a subspace of  $T_p M$ .
- We thus can restrict to  $S$  any  $k$ -covector  $\omega_p \in \Lambda^k(T_p^* M)$ ; this defines a  $k$ -covector on  $T_p S$ , i.e., an element of  $\Lambda^k(T_p^* S)$ .

## Definition

If  $\omega$  is a  $k$ -form on  $M$ , its *restriction* to  $S$ , denoted  $\omega|_S$ , is the  $k$ -form on  $S$  defined by

$$(\omega|_S)_p(v_1, \dots, v_k) = \omega_p(v_1, \dots, v_k) \quad \text{for all } p \in S \text{ and } v_i \in T_p S.$$

# Restriction of $k$ -Forms to Submanifolds

In the same way as with 1-forms we have:

## Proposition

*Let  $S$  be an immersed submanifold in  $M$ . If  $i : S \rightarrow M$  is the inclusion of  $S$  into  $M$  and  $\omega$  is a  $k$ -form on  $M$ , then  $\omega|_S = i^*\omega$ .*

As pullbacks by smooth maps preserve smoothness we get:

## Corollary

*Let  $S$  be an immersed submanifold in  $M$ . If  $\omega$  is a smooth  $k$ -form on  $M$ , then  $\omega|_S$  is a smooth  $k$ -form on  $S$ .*

# Restriction of $k$ -Forms to Submanifolds

## Corollary

Let  $S$  be an immersed submanifold in  $M$ . If  $\omega \in \Omega^k(M)$ , then

$$(d\omega)|_S = d(\omega|_S).$$

## Proof.

Let  $i : S \rightarrow M$  be the inclusion of  $S$  into  $M$ . As exterior differentiation commutes with pullback by  $i$ , we get

$$(d\omega)|_S = i^*(d\omega) = d(i^*\omega) = d(\omega|_S).$$

The result is proved. □

## Remark

As  $(d\omega)|_S$  and  $d(\omega|_S)$  agree, we simply write  $d\omega|_S$  to mean either expression.

# A Nowhere-Vanishing 1-Forms on $\mathbb{S}^1$

## Example

- The unit circle  $\mathbb{S}^1$  has equation  $x^2 + y^2 = 1$ . This a regular submanifold of  $\mathbb{R}^2$ . Thus,

$$[d(x^2 + y^2)]|_{\mathbb{S}^1} = d[(x^2 + y^2)|_{\mathbb{S}^1}] = d1 = 0.$$

- On  $\mathbb{R}^2$  we also have

$$d(x^2 + y^2) = \frac{\partial}{\partial x}(x^2 + y^2)dx + \frac{\partial}{\partial y}(x^2 + y^2)dy = 2xdx + 2ydy.$$

- Thus,

$$(xdx + ydy)|_{\mathbb{S}^1} = 0.$$

- In particular, on regions of  $\mathbb{S}^1$  where  $x \neq 0$  and  $y \neq 0$ , we have

$$\frac{dy}{x} = -\frac{dx}{y}.$$

# A Nowhere-Vanishing 1-Forms on $\mathbb{S}^1$

## Example (continued)

- Set  $U_x = \{(x, y) \in \mathbb{S}^1; x \neq 0\}$  and  $U_y = \{(x, y) \in \mathbb{S}^1; y \neq 0\}$ . Let  $\omega$  be the 1-form on  $\mathbb{S}^1$  defined by

$$\omega = \frac{dy}{x} \quad \text{on } U_x, \quad \omega = -\frac{dx}{y} \quad \text{on } U_y.$$

- This is well-defined since  $\frac{dy}{x} = -\frac{dx}{y}$  on  $U_x \cap U_y$ .
- $\omega$  is a smooth 1-form, since on both  $U_x$  and  $U_y$  it is the restriction of a smooth 1-form on an open of  $\mathbb{R}^2$ .

## Proposition (see Tu's book)

*The 1-form  $\omega$  is a nowhere-vanishing smooth 1-form on  $\mathbb{S}^1$ , i.e.,  $\omega_p \neq 0$  for all  $p \in \mathbb{S}^1$ .*